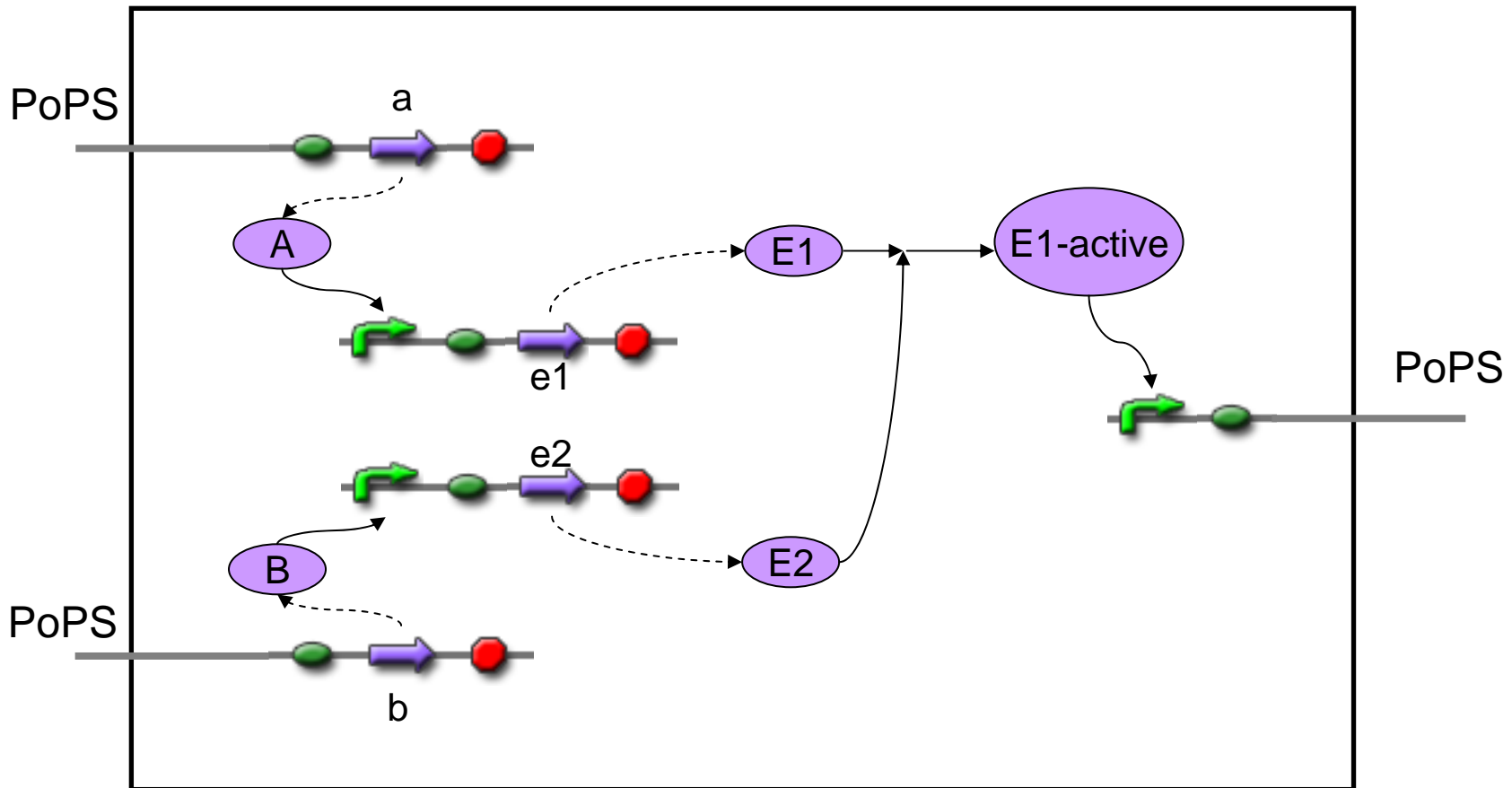


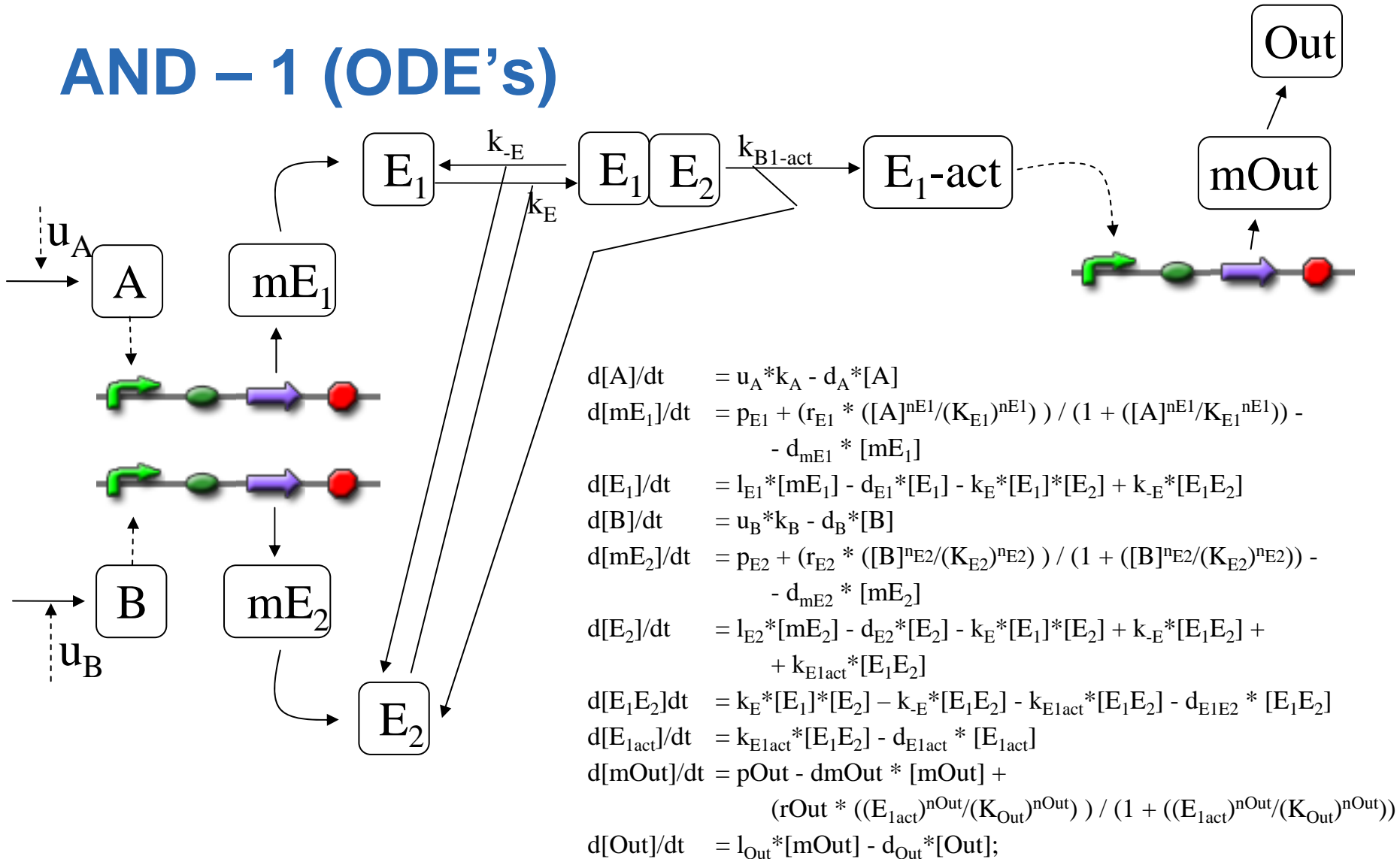
Half Adder - ODEs



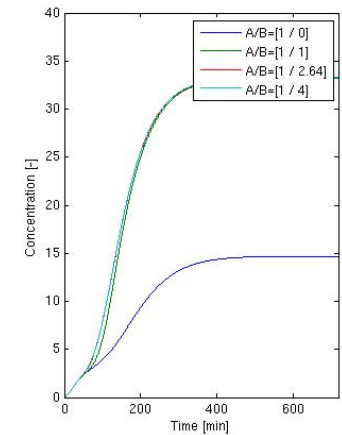
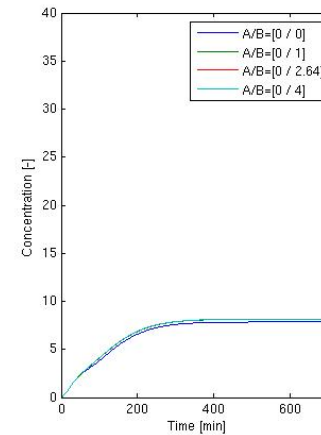
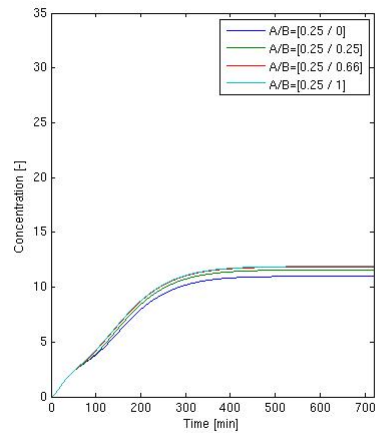
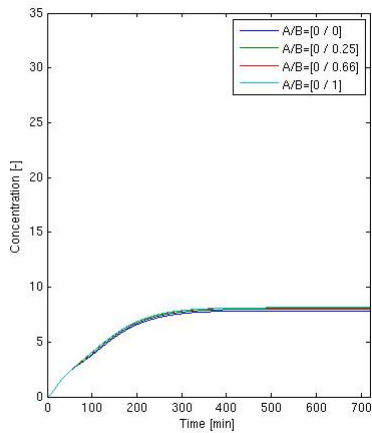
AND – 1



AND – 1 (ODE's)

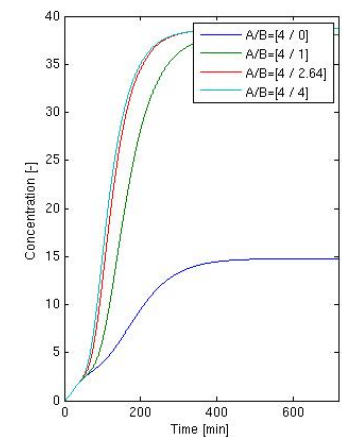
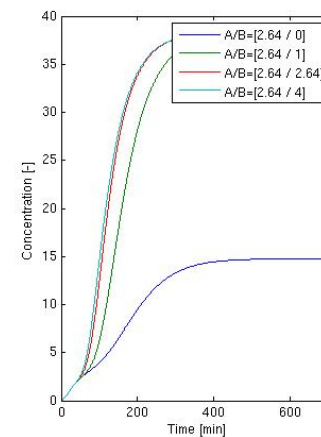
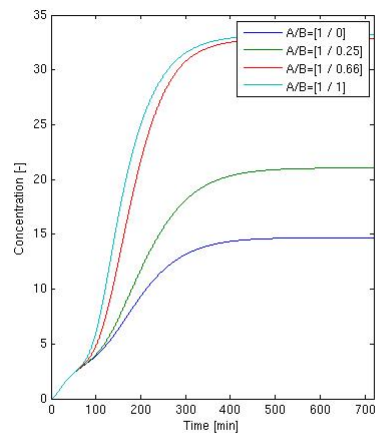
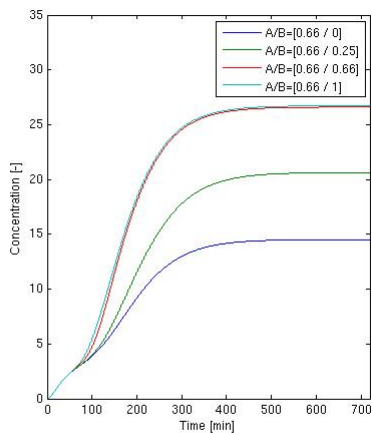


AND – 1 (simulation results)

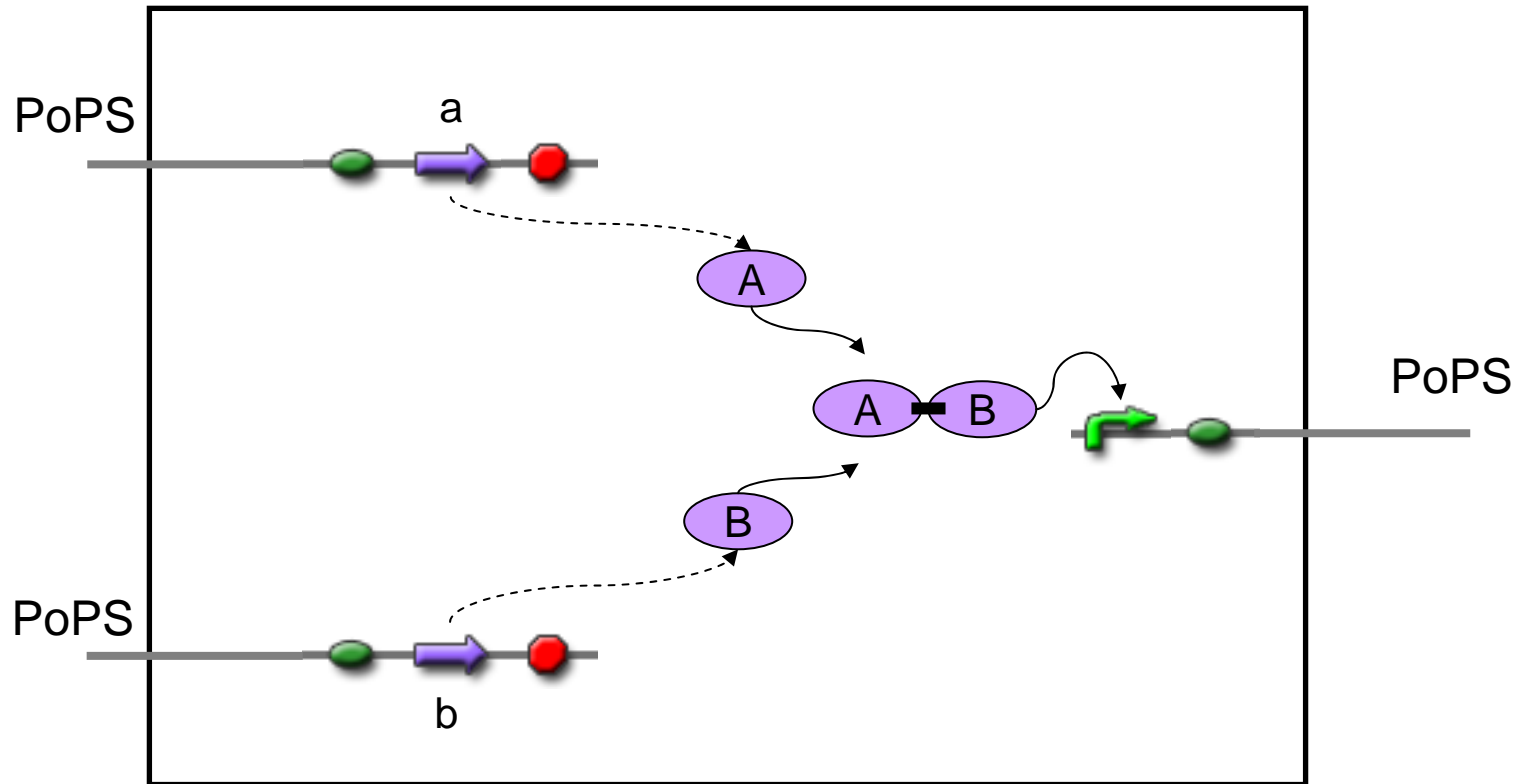


Input range 0...1

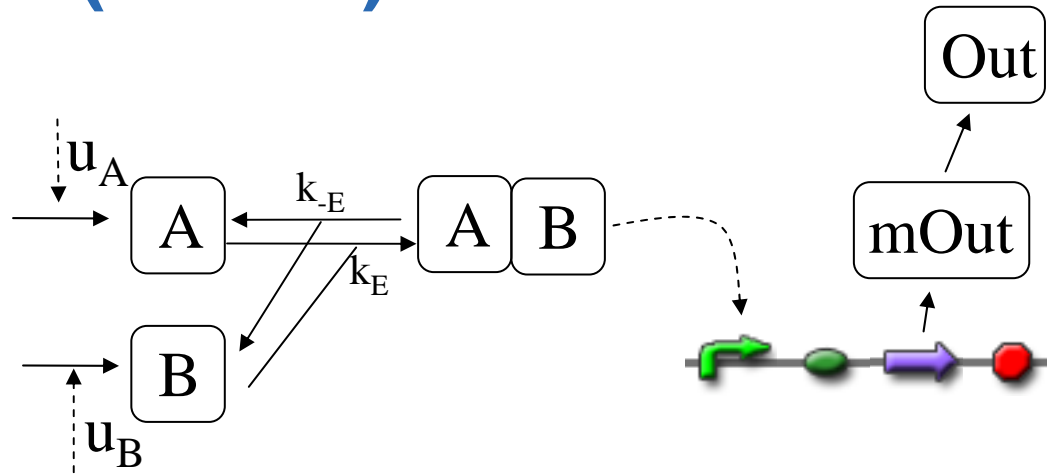
Input range 0...4



AND – 2



AND – 2 (ODE's)



$$d[A]/dt = u_A * k_A - d_A * [A] - k_{AB} * ([A] * [B])^{n_{AB}} + k_{-AB} * [AB]^{n_{AB}}$$

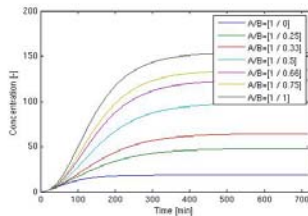
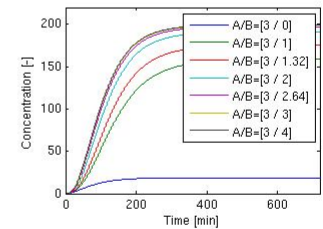
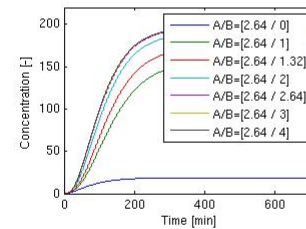
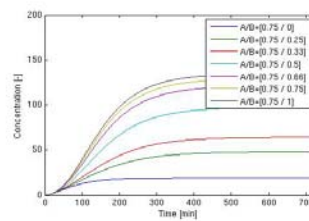
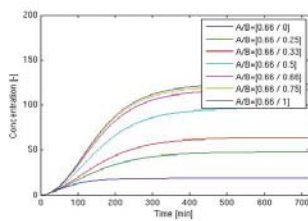
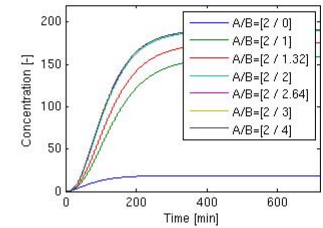
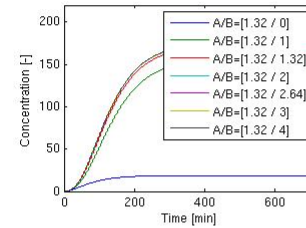
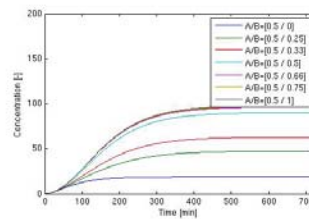
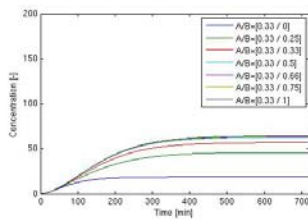
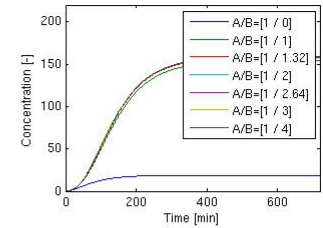
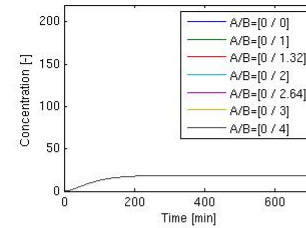
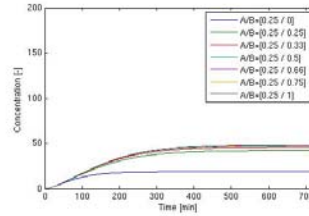
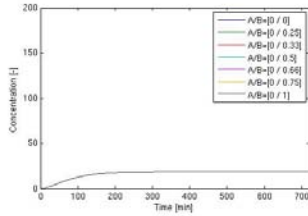
$$d[B]/dt = u_B * k_B - d_B * [B] - k_{AB} * ([A] * [B])^{n_{AB}} + k_{-AB} * [AB]^{n_{AB}}$$

$$d[AB]/dt = k_{AB} * ([A] * [B])^{n_{AB}} - k_{-AB} * [AB]^{n_{AB}} - d_{AB} * [AB]$$

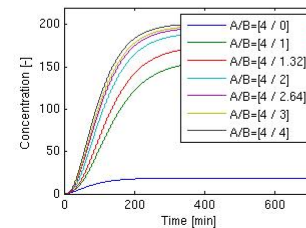
$$d[mOut]/dt = p_{Out} + (r_{Out} * ([AB]^{n_{Out}} / (K_{Out})^{n_{Out}})) / (1 + ([AB]^{n_{Out}} / (K_{Out})^{n_{Out}})) - d_{mOut} * [mOut]$$

$$d[Out]/dt = l_{Out} * [mOut] - d_{Out} * [Out]$$

AND – 2 (simulation results)



Input range 0...1



Input range 0...4